Async Rust and 9p server

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Agenda

Introduction

Motivation, async Rust, kernel implementations

9p server

Description, some implementation samples

Demo

Discussion

Motivation

Showcase productivity gains from using Rust In addition to security benefits

Considerable attack surface

For example, receiving untrusted data over the network

Pure software module

No inherent unsafety due to bus mastering devices

Started looking at ksmbd

Not an ideal initial project because of complexity of the protocol Also requires a user-space component

Async Rust

Talked about it at OSS North America: link

In summary:

Compiler automatically creates a state machine from thread-like code Kernel crate implements executors and reactors

Workqueue Executor

Spawning tasks

Allocates task: contains future plus executor-specific state (e.g., work_struct) Adds to task list Wakes task up

Waking tasks up

Enqueues task for running (e.g., queue_work_on)

On worker thread: accesses revocable task, poll future, cleans it up when it completes

Tearing down

All state is dropped (more on this later)

Socket Reactor

Initialisation

Pinned larger struct containing some state plus wait queue entry (wait_queue_entry) Wait queue entry with a custom function (init_waitqueue_func_entry) Adds entry to the socket's wait queue (add_wait_queue)

Waking up

Wait queue callback is called: uses container_of to get to outer struct Checks mask for filter callbacks (EPOLLIN, EPOLLOUT, etc) Calls Waker::wake to instruct executor to run task again

Cleaning up

Removes entry from socket's wait queue (remove_wait_queue)

9p file server

What is 9p?

Plan 9 is an operating system from Bell Labs (<u>link</u>) Originally designed by Ken Thompson, Rob Pike, et al.

Included a remote file system protocol: <u>Plan 9 File Protocol, 9P</u> The Linux kernel already includes a 9p <u>client</u> Qemu implements a server to share a host directory with guest

Straightforward: original protocol only includes 10 operations

What is implemented

Not a file system Though we have some support for it <u>here</u>

Exposes the local file system over the network

Read-only for now

Implements 9P2000.L – Linux extensions

WIP but available here

Code stats

Receiving requests

```
async fn next_pdu(&self, max_size: u32) -> Result<Box<[u8]>> {
    // Read the length.
    let mut len_in_bytes = [0u8; 4];
    self.stream.read_all(&mut len_in_bytes).await?;
    let len = u32::from_le_bytes(len_in_bytes).checked_sub(4).ok_or(EIO)?;
    if len > max_size {
        // Read the length
        //
```

```
return Err(E2BIG);
}
```

// Allocate the buffer and read the rest.
self.stream.alloc_read_exact(len as usize).await

Dispatching requests

```
loop {
    let pdu = conn.next_pdu(max_size).await?;
    let (_op, tag) = protocol::get_op_tag(&pdu)?;
    let res = spawn_task!(
        executor.as_ref_borrow(), conn.clone().handle_pdu(tag, pdu));
    if let Err(e) = res {
        conn.write_result(|b| protocol::error(b, tag, e)).await?;
    }
}
```

Serialising writes

```
async fn write(&self, buf: &[u8]) {
   let mut inner = self.inner.lock().await;
   if inner.err.is_err() {
       // A previous write failed so we won't even try this one.
       return;
   let ret = self.stream.write_all(buf).await;
   if ret.is_err() {
       // Store away the error.
       inner.err = ret;
```

Cleaning up

Executor keeps track of all incomplete tasks

Auto-stop handles stop executors when they go out of scope

Stopping an executor waits for running tasks to go to sleep Also ensures that sleeping tasks don't wake up anymore Drops all tasks

"Local variables" of async functions are also dropped Reactors unregister from subsystems Allocations are freed, ref-counted objects are released, etc.

Stopping an executor results in everything being dropped automatically

Demo

Discussion

Possible topics

Additional potential candidates to be written in async Rust Driver state machines?

Additional reactors

kiocb, urb, bio?

Implementing more non-blocking operations/primitives

Select

Communication channels (send/receive data structures)

Memory allocation (GFP_KERNEL): can we give up the worker instead of sleeping? Read-write mutexes

Condition variables

Possible topics (cont'd)

Integration with user-space implementations Tokio panics on memory allocation failures

Destruction of mutual exclusion primitives

State may be inconsistent Release the lock? Keep it locked? Poising (which implies acquisition may fail)?

Fault isolation

Should we unwind stacks, drop objects, etc. for panics in tasks? At the moment, we kill a workqueue thread Thank you!